

## **Introduction to Linear Programming (LP)**

- **Mathematical Programming Concept**
- **LP Concept**
- **Standard Form**
- **Assumptions**
- **Consequences of Assumptions**
- **Solution Approach**
- **Solution Methods**
- **Typical Formulations**

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## **Mathematical Programming (MP) Concept (1)**

- **Definition**
  - M.P. includes a range of powerful computer-based optimization methods
- **Approach to Optimization**
  - M.P. methods exploit peculiar features of the structure of a problem to get solutions efficiently
  - Different M.P. methods exploit different structures or features
  - Understanding which features apply to a particular problem -- and thus which method can apply -- is important

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## **Mathematical Programming (MP) Concept (2)**

- **Two Large Categories of Methods**
- **Those Valid for Convex Feasible Regions**
  - Linear Programming, etc
  - These use a local search routine to reach global optimum
  - “Keep going up/down until reach top/bottom”
  - Very efficient -- but not always valid
- **Those Valid for Non-Convex Feasible Regions**
  - Dynamic programming, etc
  - These “enumerate” solutions to discover optimum
  - They “prune,” that is, eliminate, possible solutions because these can be shown to be “dominated”
  - Computations limit applicability to special situations, but good for options analysis

## **LP Overview**

- **Special form of mathematical programming**
  - Equations must be linear
- **Uses simple solution procedures**
  - Linear algebra
- **Very powerful**
  - Extremely large problems
  - 100,000 variables
  - 1000's of constraints
- **Note difference!**
- **Useful design information through Sensitivity Analysis**
  - Answers to “what if” questions

## Standard Form of LP - Three Parts

### ▪Objective function

–maximize or  
minimize



$$\begin{aligned} \text{▪ } Y &= \sum c_i x_i \\ \text{▪ } Y &= c_1 x_1 + c_2 x_2 + \dots + c_n x_n \end{aligned}$$

$x_i$  known as decision variables

### ▪Constraints

–subject to:



$$\begin{aligned} \text{▪ } a_{11}x_1 + a_{12}x_2 + \dots &< = > b_1 \\ \text{▪ } a_{21}x_1 + a_{22}x_2 + \dots &< = > b_2 \\ \text{▪ } a_{31}x_1 + a_{32}x_2 + \dots &< = > b_3 \end{aligned}$$

### ▪Non-Negativity



$$\text{▪ } x_i \geq 0 \text{ for all } i$$

## Standard Form of LP -- Summary

Optimize

$$Y = \underline{c} \underline{X}$$

subject to:

$$\underline{A} \underline{X} (< \text{ or } = \text{ or } >) \underline{b}$$

$$\underline{X} \geq 0$$

## Three LP Assumptions (1)

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- **Linearity**
- **Additivity**
- **Non-Negativity**
- **Linearity of Objective Function and Constraints**
  - Essential Condition is:
$$f(k\underline{X}) = k f(\underline{X})$$
  - for example:  $f(\underline{X}) = 3 + 4X_1 + 2X_2$   
is NOT linear in the LP sense
- **Implies**
  - Constant returns to scale (only first order terms)
  - No "fixed charges" (no constants)

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## Three LP Assumptions (2)

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- **Additivity:**
$$f(X_1, X_2, \dots, X_n) = f(X_1) + f(X_2) + \dots + f(X_n)$$
  - no interactive effects among  $X_i$  terms
  - assumes that individual segments of the problem operate as well independently as together
- **Non-Negativity**
$$X_i > 0$$
  - no fundamental difficulties except in particular situations

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## Consequences of Assumptions

- Convexity of feasible region (if it exists!)
- Convex feasible region, with linear objective function, implies:
  - Optimum will be on an edge of the feasible region
- Since edges are also linear
  - Optimum is at a corner point (can be several in special cases)
- Note that corner points
  - Constitute small, finite set
  - Defined by solution of linear equations

**Bottom Line:** Assumptions imply the existence of an efficient solution strategy

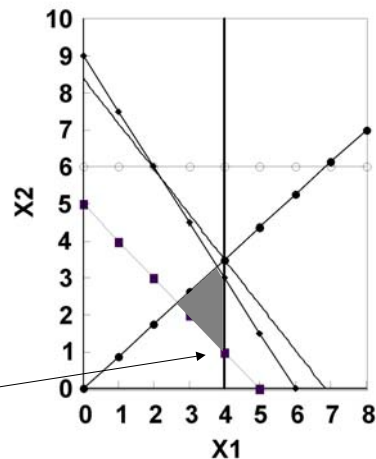
## Example for Assumptions

minimize:  $Z = 3X_1 + 5X_2$

s.t.  $X_1 + X_2 \geq 5$   
 $3X_1 + 2X_2 \leq 18$   
 $6X_1 + 5X_2 \leq 42$   
 $-7X_1 + 8X_2 \leq 0$   
 $0 \leq X_1 \leq 4$   
 $0 \leq X_2 \leq 6$

$X_1^* = 4$

$X_2^* = 1$



## **Solution Approach**

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- **Find a corner point**
  - An "initial feasible solution"
- **Proceed to improved corner points**
- **Stop when no further improvements are possible**

## **Solution Calculations**

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- **To find a corner point**
  - it is necessary to solve system of constraint equations
  - from linear algebra, this requires working with matrix of constraint equations, specifically, manipulating the "determinants"
  - Amount of effort set by number of constraints
- **Thus, number of constraints defines amount of effort**
- **This is why LP can handle many more decision variables than constraints**

## Solution Methods

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### ▪Simplex

- The textbook method
- For step 2, select improved corners
  - Always goes to best corner
  - Searches until no further improvement possible
- Inefficient for real problems
- Not used in practice

### ▪Practical methods - many exist - often proprietary

- Step 2 takes many forms
- Each best for different cases
- Very great efficiency possible
- A real art!

## Excel LP Methods

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### •Several LP methods available for simple problems

- What's Best <http://www.lindo.com/cgi-bin/>
- Solver an Excel tool

### •These methods use standard equation and need no special organization

### •They provide all kinds of sensitivity information

### •The difficult part is setting up the LP equations so that they make sense!

## Typical Formulations: "Transportation" Problem

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**Objective** = Minimize cost of moving a single commodity from sources "i" to uses "j"  
$$= \sum C_{ij} X_{ij}$$

**subject to:**

**Amount shipped** < **Amount available**       $\sum_j X_{ij} \leq S_i$

**Amount delivered** > **Uses**       $\sum_i X_{ij} \geq S_j$

**Note:**

**Matrix of constraint coefficients are all 0's and 1's**  
–Particularly efficient solutions

## Typical Formulations: "Blending" or "Diet" Problems

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**Objective** = Minimize cost of materials  
$$= \sum C_i X_i$$

**subject to:**

**Limits on availability**       $X_i \leq \text{Amounts given}$

**Maxima or minima on impurities, trace elements,  
nutritional requirements, etc...**       $\sum a_{ij} X_i \leq = \geq b_j$

**Example:**

–Minimize cost of steel alloy when only so much scrap is available, subject to limitations on carbon content, trace elements, etc.



## Typical Formulations: “Activity” Problems

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**Objective** = Minimize cost of production  
=  $\sum C_i X_i$

where  $X_i$  represent “activities”, that is, specific ways  
or fixed ratios of using resources

**subject to:**

**Limits on resources**  $\sum a_{ij} X_i \leq = \geq b_j$

**Example:**

–Minimize cost of delivering cargo where each “activity”  
represents the use of a different size of ship, each with its own  
implications for the use of crew, fuel, etc.

## Summary

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- LP can handle very large problems
- Basic mathematics simple
- User can focus on definition of the problem
- Realistic problems require special techniques to deal with non-linearities, integral variables, etc. Can be very sophisticated
- This presentation is only an introduction!